

# 17. Triple Integrals Part 2, Change of Variables

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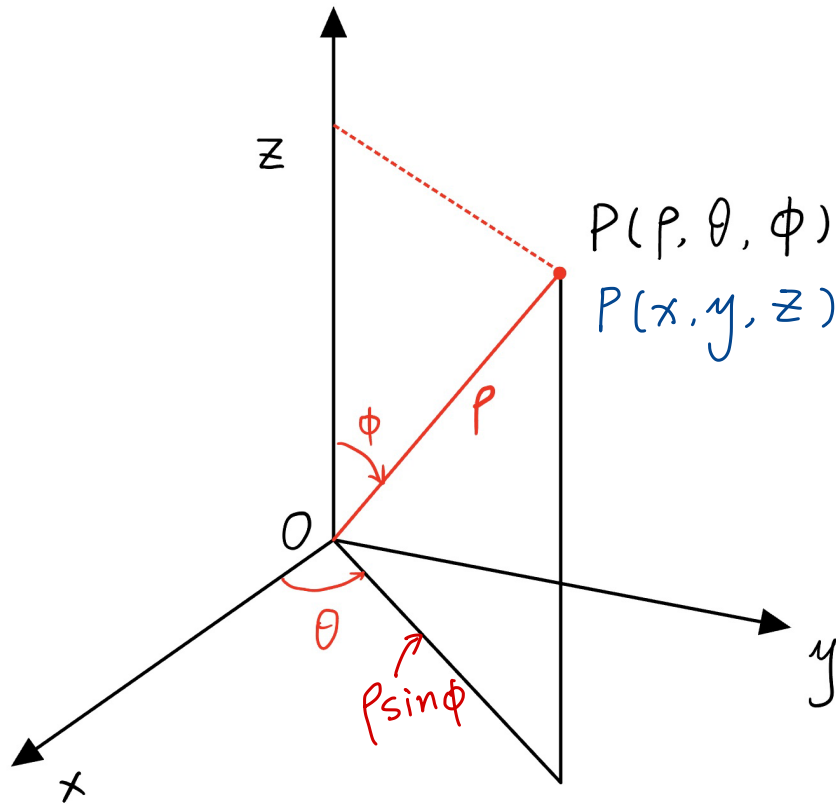
In this lecture, we will discuss

- Triple Integrals in Cylindrical and Spherical Coordinates, Part 1
  - Change of Variables in Multiple Integrals
    - Change of Variables in Double Integrals
      - Jacobian of the transformation
      - Application: Revisit the Change to Polar Coordinates in a Double Integral
    - Change of Variables in Triple Integrals
      - Jacobian of the transformation
      - Application: Revisit the Change to Spherical Coordinates in a Triple Integral
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## Spherical Coordinates

Recall from Lecture 7, we define the spherical coordinates  $(\rho, \theta, \phi)$  of a point (see the figure below). The relationships between the spherical coordinates and the rectangular coordinates are:

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$



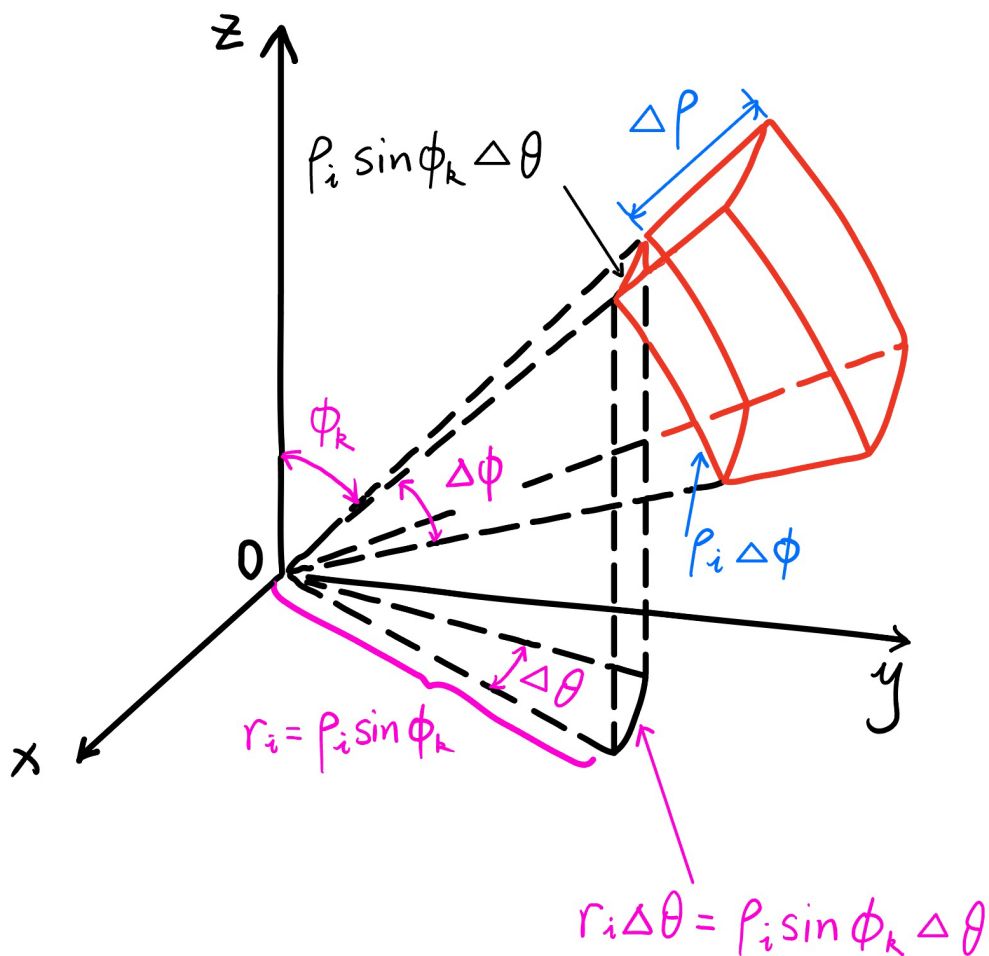
**The spherical coordinates of a point**

- In the spherical coordinate system the counterpart of a rectangular box is a spherical wedge

$$E = \{(\rho, \theta, \phi) \mid a \leq \rho \leq b, \alpha \leq \theta \leq \beta, c \leq \phi \leq d\}$$

where  $a \geq 0$  and  $\beta - \alpha \leq 2\pi$ .

- It can be shown that dividing a solid into small spherical wedges always gives the same result as dividing it into small boxes.
- So we divide  $E$  into smaller spherical wedges  $E_{ijk}$  by means of equally spaced spheres  $\rho = \rho_i$ , half-planes  $\theta = \theta_j$ , and half-cones  $\phi = \phi_k$  as the figure below.



- The above figure shows that  $E_{ijk}$  is approximately a rectangular box with dimensions  $\Delta\rho$ ,  $\rho_i\Delta\phi$  (arc of a circle with radius  $\rho_i$ , angle  $\Delta\phi$ ), and  $\rho_i \sin \phi_k \Delta\theta$  (arc of a circle with radius  $\rho_i \sin \phi_k$ , angle  $\Delta\theta$ ).
- So an approximation to the volume of  $E_{ijk}$  is given by

$$(\Delta\rho) \times (\rho_i\Delta\phi) \times (\rho_i \sin \phi_k \Delta\theta) = \rho_i^2 \sin \phi_k \Delta\rho \Delta\theta \Delta\phi$$

- Thus, an approximation to a typical triple Riemann sum is

$$\sum_{i=1}^l \sum_{j=1}^m \sum_{k=1}^n f(\rho_i \sin \phi_k \cos \theta_j, \rho_i \sin \phi_k \sin \theta_j, \rho_i \cos \phi_k) \rho_i^2 \sin \phi_k \Delta\rho \Delta\theta \Delta\phi$$

- Note this sum is a Riemann sum for the function

$$F(\rho, \theta, \phi) = f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \cdot \rho^2 \sin \phi$$

- Thus we have the following formula

### Theorem. Formula for Triple Integration in Spherical Coordinates

$$\begin{aligned} \iiint_E f(x, y, z) dV \\ = \int_c^d \int_\alpha^\beta \int_a^b f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi \end{aligned} \quad (1)$$

where  $E$  is a spherical wedge given by

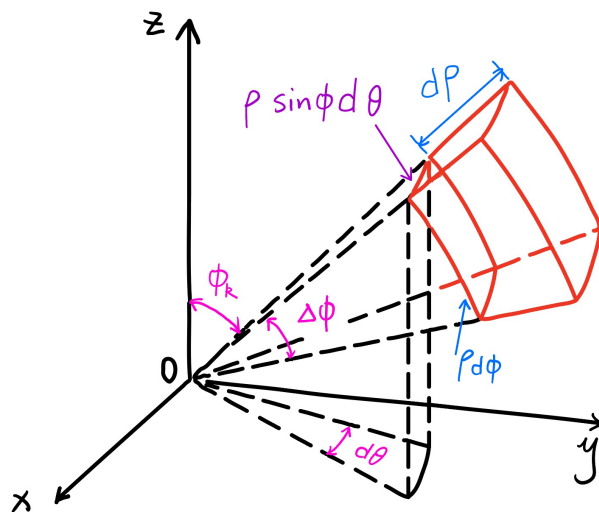
$$E = \{(\rho, \theta, \phi) \mid a \leq \rho \leq b, \alpha \leq \theta \leq \beta, c \leq \phi \leq d\}$$

#### Remark.

- Equation (1) states that we can convert a triple integral from rectangular coordinates to spherical coordinates by writing

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

using the appropriate limits of integration, and replacing  $dV$  by  $\rho^2 \sin \phi d\rho d\theta d\phi$ . This is explained by the figure below.



$$dV = \rho^2 \sin \phi d\rho d\theta d\phi$$

Volume Element in Spherical Coordinates

- More generally, we can have the spherical regions like

$$E = \{(\rho, \theta, \phi) \mid \alpha \leq \theta \leq \beta, c \leq \phi \leq d, g_1(\theta, \phi) \leq \rho \leq g_2(\theta, \phi)\}$$

In this case the formula is the same as in Equation (1) except that the limits of integration for  $\rho$  are  $g_1(\theta, \phi)$  and  $g_2(\theta, \phi)$ .

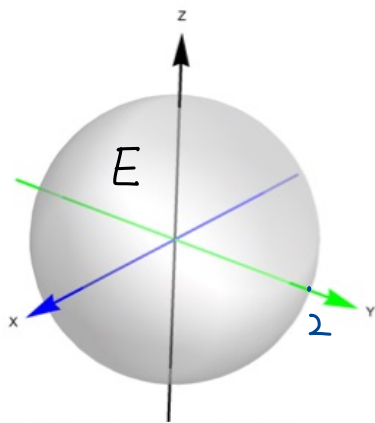
- Usually, spherical coordinates are used in triple integrals when surfaces such as cones and spheres form the boundary of the region of integration.

**Example 1.** Use spherical coordinates to evaluate the triple integral  $\iiint_{\mathbf{E}} x^2 + y^2 + z^2 dV$ , where  $\mathbf{E}$  is the ball:  $x^2 + y^2 + z^2 \leq 4$ .

ANS: The solid  $E$  can be described by spherical coordinates

$$E = \{(\rho, \theta, \phi) \mid 0 \leq \rho \leq 2, 0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi\}$$

Thus by Eq(1), we have.



**Theorem. Formula for Triple Integration in Spherical Coordinates**

$$\begin{aligned} \iiint_E f(x, y, z) dV \\ = \int_c^d \int_\alpha^\beta \int_a^b f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi \end{aligned}$$

(1)

where  $E$  is a spherical wedge given by

$$E = \{(\rho, \theta, \phi) \mid a \leq \rho \leq b, \alpha \leq \theta \leq \beta, c \leq \phi \leq d\}$$

$$\begin{aligned} \iiint_E x^2 + y^2 + z^2 dV \\ = \int_0^\pi \int_0^{2\pi} \int_0^2 \left( (\rho \sin \phi \cos \theta)^2 + (\rho \sin \phi \sin \theta)^2 + (\rho \cos \phi)^2 \right) \rho^2 \sin \phi d\rho d\theta d\phi \end{aligned}$$

$$= \int_0^\pi \int_0^{2\pi} \int_0^2 \rho^2 \cdot \rho^2 \sin \phi d\rho d\theta d\phi$$

$$= \int_0^\pi \int_0^{2\pi} \int_0^2 \rho^4 \sin \phi d\rho d\theta d\phi$$

$$= \int_0^\pi \int_0^{2\pi} \left. \frac{1}{5} \rho^5 \sin \phi \right|_{\rho=0}^{\rho=2} d\theta d\phi$$

$$= \frac{2^5}{5} \int_0^\pi \int_0^{2\pi} \sin \phi d\theta d\phi$$

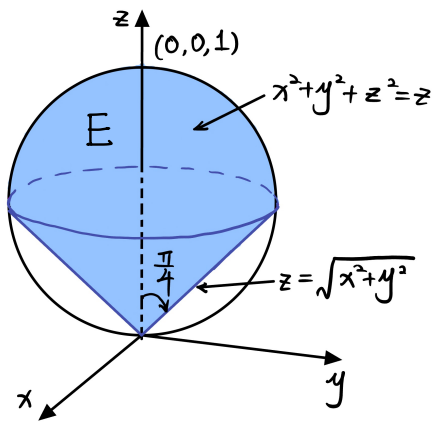
$$= \frac{2^5}{5} \int_0^{2\pi} 1 d\theta \int_0^\pi \sin \phi d\phi$$

$$= \frac{2^5}{5} \cdot \theta \Big|_0^{2\pi} \cdot [-\cos \phi] \Big|_0^\pi$$

$$= \frac{2^5}{5} \cdot 2\pi \cdot 2$$

$$= \frac{2^7}{5} \pi$$

**Example 2.** Use spherical coordinates to find the volume of the solid that lies above the cone  $z = \sqrt{x^2 + y^2}$  and below the sphere  $x^2 + y^2 + z^2 = z$ .



ANS: Denote the solid by E

$$x^2 + y^2 + z^2 = z$$

$$\Rightarrow x^2 + y^2 + z^2 - z + \frac{1}{4} = \frac{1}{4}$$

$$\Rightarrow x^2 + y^2 + \left(z - \frac{1}{2}\right)^2 = \left(\frac{1}{2}\right)^2$$

Thus  $x^2 + y^2 + z^2 = z$  is a sphere centered at  $(0, 0, \frac{1}{2})$  with radius  $\frac{1}{2}$ .

In spherical coordinates, the sphere can be written as

$$x^2 + y^2 + z^2 = \rho^2 = z = \rho \cos \phi \Rightarrow \rho = \cos \phi$$

Also, the equation of the cone can be written as

$$z = \sqrt{x^2 + y^2}$$

$$\Rightarrow \rho \cos \phi = \sqrt{(\rho \sin \phi \cos \theta)^2 + (\rho \sin \phi \sin \theta)^2} = \sqrt{\rho^2 \sin^2 \phi}$$

$$= \rho \sin \phi$$

$$\Rightarrow \rho \cos \phi = \rho \sin \phi$$

This implies  $\cos \phi = \sin \phi \Rightarrow \phi = \frac{\pi}{4}$

Thus the solid E can be described by the spherical coordinates as

$$0 \leq \theta \leq 2\pi$$

$$0 \leq \phi \leq \frac{\pi}{4}$$

$$0 \leq \rho \leq \cos \phi$$

Thus

$$V_0(E) = \iiint dV$$

$$= \int_0^{2\pi} \int_0^{\frac{\pi}{4}} \int_0^{\cos \phi} \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$

$$= \int_0^{2\pi} \int_0^{\frac{\pi}{4}} \left. \frac{1}{3} \rho^3 \sin \phi \right|_{\rho=0}^{\rho=\cos \phi} d\phi \, d\theta$$

$$= \frac{1}{3} \int_0^{2\pi} \int_0^{\frac{\pi}{4}} \cos^3 \phi \sin \phi \, d\phi \, d\theta$$

$$= \frac{1}{3} \int_0^{2\pi} \int_0^{\frac{\pi}{4}} -\cos^3 \phi \, d(\cos \phi) \, d\theta$$

$$= \frac{1}{3} \int_0^{2\pi} \left. -\frac{1}{4} \cos^4 \phi \right|_0^{\frac{\pi}{4}} d\theta$$

$$= \frac{1}{3} \left( \int_0^{2\pi} d\theta \right) \left( -\frac{1}{4} \left[ \cos^4 \frac{\pi}{4} - \cos^4 0 \right] \right)$$

$$= \frac{2\pi}{3} \left( -\frac{1}{4} \left( \left( \frac{1}{\sqrt{2}} \right)^4 - 1 \right) \right)$$

$$= \frac{2\pi}{3} \cdot \frac{3}{16}$$

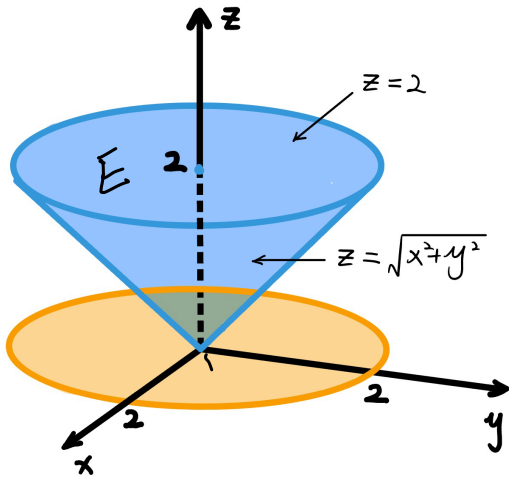
$$= \frac{\pi}{8}$$

## Review on cylindrical coordinates

**Example 3.** Evaluate the integral by changing to cylindrical coordinates:

$$\int_{-2}^2 \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \int_{\sqrt{x^2+y^2}}^2 (x^2 + y^2) dz dy dx$$

Below is a figure of the solid region of integration that might help with the calculation.



The region  $E$  in terms of rectangle coordinate is

$$\sqrt{x^2+y^2} \leq z \leq 2$$

$$-\sqrt{4-x^2} \leq y \leq \sqrt{4-x^2}$$

$$-2 \leq x \leq 2$$

Note the projection of  $E$  onto  $xy$ -plane is the disk  $x^2+y^2 \leq 4$ . Thus  $E$  is easier to describe in terms of cylindrical coordinate.

$$E: \sqrt{x^2+y^2} = r \leq z \leq 2$$

$$0 \leq \theta \leq 2\pi$$

$$0 \leq r \leq 2$$

$$\text{Thus } \int_{-2}^2 \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \int_{\sqrt{x^2+y^2}}^2 (x^2 + y^2) dz dy dx$$

$$= \iiint_E (x^2 + y^2) dV$$

$$= \int_0^{2\pi} \int_0^2 \int_r^2 r^2 r dz dr d\theta$$

$$= \int_0^{2\pi} d\theta \int_0^2 \int_r^2 r^3 dz dr$$



$$= 2\pi \cdot \int_0^2 r^3 \cdot z \Big|_{z=r}^{z=2} dr$$

$$= 2\pi \int_0^2 (2r^3 - r^4) dr$$

$$= 2\pi \left[ \frac{1}{2} r^4 - \frac{1}{5} r^5 \right] \Big|_0^2$$

$$= 2\pi \left[ 8 - \frac{32}{5} \right]$$

$$= 2\pi \cdot \frac{8}{5}$$

$$= \frac{16\pi}{5}$$

## Change of Variables in Multiple Integrals

### Change of Variable in one-dimensional calculus

Recall in calculus, we have the change of the variable formula:

$$\int_a^b f(x)dx = \int_c^d f(g(u))g'(u)du$$

where  $x = g(u)$  and  $a = g(c)$ ,  $b = g(d)$ .

And we can rewrite it as

$$\int_a^b f(x)dx = \int_c^d f(x(u))\frac{dx}{du}du \quad (2)$$

Next, we are going to see the generalization of equation (2) to higher dimensions (these are Equation (7) and (8)).

### Change of Variable in double integrals

- A change of variables can also be used in double integrals.
- One example is the conversion to polar coordinates.
- The new variables  $r$  and  $\theta$  are related to the old variables  $x$  and  $y$  by the equations

$$x = r \cos \theta \quad y = r \sin \theta$$

and the change of variables formula can be written as (Lecture 15)

$$\iint_R f(x, y)dA = \iint_S f(r \cos \theta, r \sin \theta)rdrd\theta,$$

where  $S$  is the region in the  $r\theta$ -plane that corresponds to the region  $R$  in the  $xy$ -plane.

- Generally, we consider a change of variables that is given by a vector-valued function  $T$  from the  $uv$ -plane to the  $xy$ -plane:

$$T(u, v) = (x, y)$$

where  $x$  and  $y$  are related to  $u$  and  $v$  by the equations

$$x = g(u, v) \quad y = h(u, v) \quad (3)$$

or, as we sometimes write,

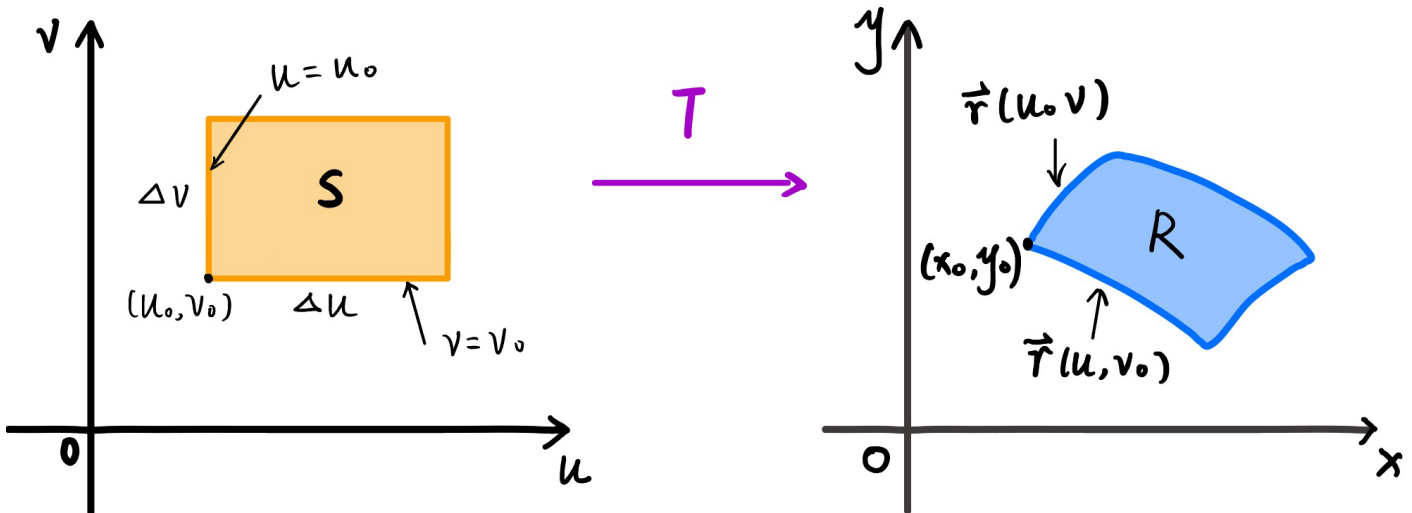
$$x = x(u, v) \quad y = y(u, v)$$

- We usually assume that  $T$  is a  $C^1$  function, which means that  $g$  and  $h$  have continuous first-order partial derivatives.

- If  $T$  is a one-to-one transformation, then it has an inverse transformation  $T^{-1}$  from the  $xy$ -plane to the  $uv$ -plane and it may be possible to solve Equations (3) for  $u$  and  $v$  in terms of  $x$  and  $y$ :

$$u = G(x, y) \quad v = H(x, y)$$

- A natural question to ask is **how a change of variables affects a double integral**.
- To answer this question, we look at a small rectangle  $S$  in the  $uv$ -plane whose lower left corner is the point  $(u_0, v_0)$  and whose dimensions are  $\Delta u$  and  $\Delta v$  in the following figure.



- The image of  $S$  is a region  $R$  in the  $xy$ -plane, one of whose boundary points is  $(x_0, y_0) = T(u_0, v_0)$ .
- The vector

$$\mathbf{r}(u, v) = g(u, v)\mathbf{i} + h(u, v)\mathbf{j}$$

is the position vector of the image of the point  $(u, v)$ .

- The equation of the lower side of  $S$  is  $v = v_0$ , whose image curve is given by the vector function  $\mathbf{r}(u, v_0)$ .
- The tangent vector at  $(x_0, y_0)$  to this image curve is

$$\mathbf{r}_u = g_u(u_0, v_0)\mathbf{i} + h_u(u_0, v_0)\mathbf{j} = \frac{\partial x}{\partial u}\mathbf{i} + \frac{\partial y}{\partial u}\mathbf{j}$$

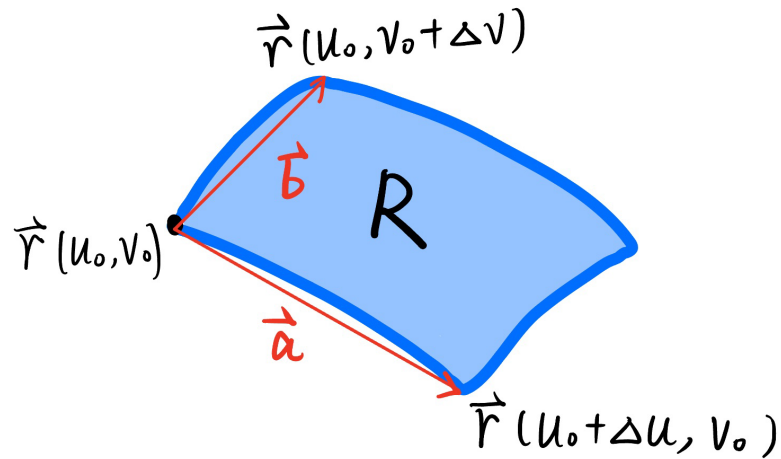
- Similarly, the tangent vector at  $(x_0, y_0)$  to the image curve of the left side of  $S$  (namely,  $u = u_0$ ) is

$$\mathbf{r}_v = g_v(u_0, v_0)\mathbf{i} + h_v(u_0, v_0)\mathbf{j} = \frac{\partial x}{\partial v}\mathbf{i} + \frac{\partial y}{\partial v}\mathbf{j}$$

- We can approximate the image region  $R = T(S)$  by a parallelogram determined by the secant vectors

$$\mathbf{a} = \mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0) \quad \mathbf{b} = \mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0)$$

as described in the following figure.



- Note

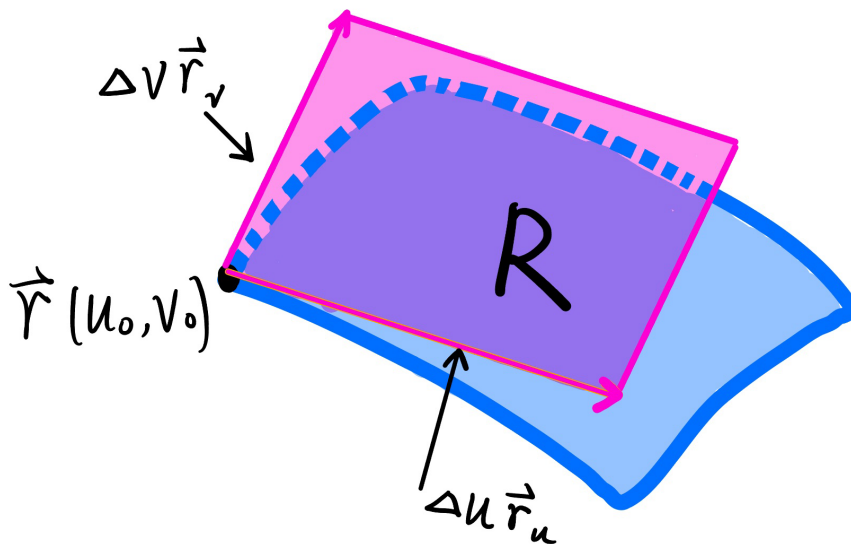
$$\mathbf{r}_u = \lim_{\Delta u \rightarrow 0} \frac{\mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0)}{\Delta u}$$

- Thus

$$\mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0) \approx \Delta u \mathbf{r}_u$$

$$\mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0) \approx \Delta v \mathbf{r}_v$$

- Therefore, we can approximate  $R$  by a parallelogram determined by the vectors  $\Delta u \mathbf{r}_u$  and  $\Delta v \mathbf{r}_v$  in the following figure.



- Thus we can approximate the area of  $R$  by the area of this parallelogram, that is ,

$$|(\Delta u \mathbf{r}_u) \times (\Delta v \mathbf{r}_v)| = |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v \quad (4)$$

- Computing the cross product, we get

$$\mathbf{r}_u \times \mathbf{r}_v = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k}$$

- Notice the matrix inside of the determinant above is the matrix  $DT$ , the derivative of the function of  $T$ .
- The above determinant is called the **Jacobian determinant** of  $T$ . Note sometimes it is also called the Jacobian in some references.

### Definition Jacobian determinant of a Function $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

The **Jacobian determinant** of the function  $T$  given by  $x = g(u, v)$  and  $y = h(u, v)$  is

$$\frac{\partial(x, y)}{\partial(u, v)} = \det(DT) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \quad (5)$$

- Then using Equation (4), we have an approximation of the area of  $R$ :

$$\Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v \quad (6)$$

where the Jacobian determinant is evaluated at  $(u_0, v_0)$ .

- Next, we consider the image of a small rectangles  $S_{ij}$  and call their images in the  $xy$ -plane  $R_{ij}$  as in the following figure:
- Applying the approximation (6) to each  $R_{ij}$ , we approximate the double integral of  $f$  over  $R$  As:

$$\begin{aligned} \iint_R f(x, y) dA &\approx \sum_{i=1}^m \sum_{j=1}^n f(x_i, y_j) \Delta A \\ &\approx \sum_{i=1}^m \sum_{j=1}^n f(g(u_i, v_j), h(u_i, v_j)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v \end{aligned}$$

where the Jacobian determinant is evaluated at  $(u_i, v_j)$ .

- Notice that the double sum is a Riemann sum for the integral

$$\iint_S f(g(u, v), h(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

The above discussion implies the following theorem:

### Theorem 1 Change of Variables in a Double Integral

Let  $D$  and  $D^*$  be elementary regions in  $\mathbb{R}^2$  and let  $T : D^* \rightarrow D$  be a  $C^1$ , one-to-one map such that  $T(D^*) = D$ . For any integrable function  $f : D \rightarrow \mathbb{R}$ ,

$$\iint_D f(x, y) dA = \iint_{D^*} f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| dA^*, \quad (7)$$

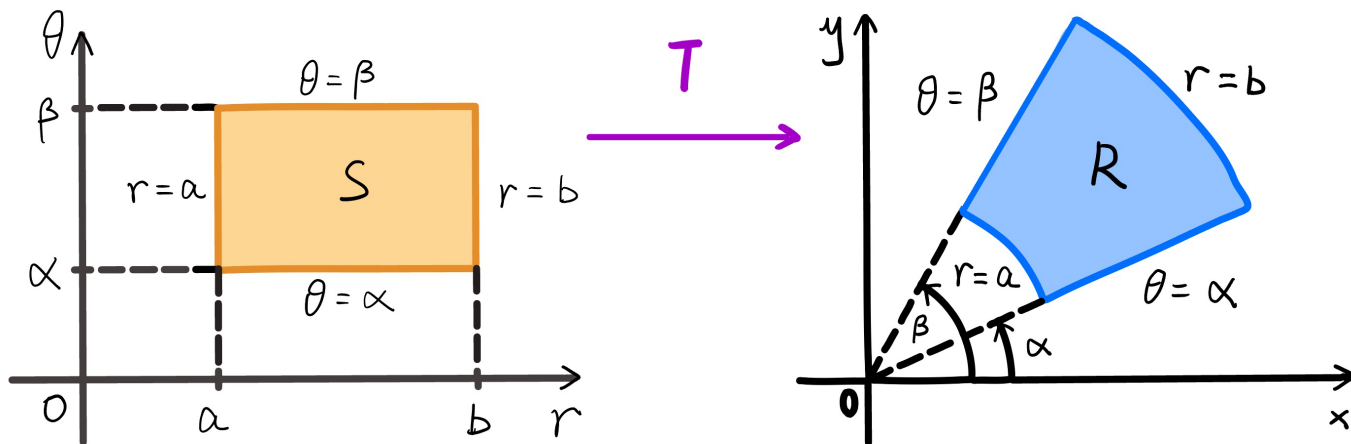
where  $\frac{\partial(x, y)}{\partial(u, v)}$  is the Jacobian determinant of  $T$ .

### Application: Revisit the Change to Polar Coordinates in a Double Integral

- We will show that the formula for integration in polar coordinates is a special case of formula (7).
- Here the function  $T$  from the  $r\theta$ -plane to the  $xy$ -plane is given by

$$x = g(r, \theta) = r \cos \theta \quad y = h(r, \theta) = r \sin \theta$$

and the geometry of the transformation is shown below.



- $T$  maps an ordinary rectangle in the  $r\theta$ -plane to a polar rectangle in the  $xy$ -plane.
- The Jacobian determinant of  $T$  is

$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r > 0$$

- Thus Theorem 1 implies

$$\begin{aligned}\iint_R f(x, y) dx dy &= \iint_S f(r \cos \theta, r \sin \theta) \left| \frac{\partial(x, y)}{\partial(r, \theta)} \right| dr d\theta \\ &= \int_\alpha^\beta \int_a^b f(r \cos \theta, r \sin \theta) r dr d\theta\end{aligned}$$

which is the same as the formula in Lecture 15.

## Change of Variables in Triple Integrals

There is a similar change of variables formula to Theorem 1 for triple integrals.

Let  $T$  be a transformation that maps a region  $S$  in  $uvw$ -space onto a region  $R$  in  $xyz$ -space by equations

$$x = g(u, v, w) \quad y = h(u, v, w) \quad z = k(u, v, w)$$

The Jacobian determinant of  $T$  is the following  $3 \times 3$  determinant:

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = \det(DT) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

Similar to Theorem 1, we have the following [formula for the change of variables in triple integrals](#):

$$\iiint_R f(x, y, z) dV = \iiint_S f(x(u, v, w), y(u, v, w), z(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| du dv dw \quad (8)$$

**Example 5.** Compute the Jacobian for the change of variables into spherical coordinates:

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta, \quad z = \rho \cos \phi$$

Then use Formula (8) to derive the formula for triple integration in spherical coordinates.

**Solution.**

We compute the Jacobian determinate as follows:

$$\frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} = \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \\ \cos \phi & 0 & -\rho \sin \phi \end{vmatrix}$$

Expanding the determinate in terms of the 3rd row, we get

$$\begin{aligned} & \cos \phi \begin{vmatrix} -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \end{vmatrix} - \rho \sin \phi \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta \end{vmatrix} \\ &= \cos \phi (-\rho^2 \sin \phi \cos \phi \sin^2 \theta - \rho^2 \sin \phi \cos \phi \cos^2 \theta) \\ & \quad - \rho \sin \phi (\rho \sin^2 \phi \cos^2 \theta + \rho \sin^2 \phi \sin^2 \theta) \end{aligned}$$

Since  $0 \leq \phi \leq \pi$ , we have  $\sin \phi \geq 0$ . Therefore

$$\left| \frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} \right| = |-\rho^2 \sin \phi| = \rho^2 \sin \phi$$

and Formula (8) implies

$$\iiint_R f(x, y, z) dV = \iiint_S f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi$$

which is equivalent to Formula (1).